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Contribution of new technologies for the monitoring of hydraulic plants: the EDF experience

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EDF context

- EDF has to monitor several hundreds kilometers dykes in France to prevent them from breakthroughs
- Currently, visual inspections are done to detect leaks which can constitute a risk in a long time

EDF objective

- □ EDF searches for a continuous measurement capable of "seeing" leaks
- □ Thermometry has then been chosen by making the following hypothesis:
 - if there is no leak, the soil temperature should be quite near from the air one
 - if there is a leak, the soil temperature should be quite near from the water one
- The only way to make this distance-along temperature measurement is using the fiber optic



- Measuring temperature with fiber optic : how does it work ?
 - Raman effect: a fiber optic excited with a laser backscatters two waves with a different frequency than that emitted, these two waves are called Stokes and Anti-Stokes
 - □ Temperature is linked with the ratio between Stokes and Anti-Stokes intensities thanks to the Boltzmann factor: $\frac{R(T) - \left(\frac{\lambda_s}{2}\right)^4}{\exp\left(\frac{h\nu_0}{2}\right)}$

$$R(T) = \left(\frac{\lambda_s}{\lambda_a}\right) \exp\left(-\frac{h\nu_0}{kT}\right)$$

 The first devices using this effect appear in 1985, but the technology is really useful with a sufficient precision since about 2000





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Technology principles

- The measurement system consists in an interrogator which emits the laser impulsions and receives the backscattered light and in a fiber optic which can be several kilometers long
- The measurement relies on the optical time-domain reflectometry (OTDR): it exploits the equivalence between time and distance to extract the information at a given position





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EDF implementation

- The fiber optic has been installed at the bottom of the downstream facing of dykes to monitor potential leaks at a depth of minimum 80 cm.
- The temperature profiles are acquired every two hours during several months
- The resulting data are so time-distance 2D arrays which are to process to extract the desired information
- Studies made using these data
 - Detection and localization of leaks using blind source separation techniques: thesis of A.A. Khan (2006-2009) with the Gipsa-lab laboratory in Grenoble (France)
 - Quantification of the Darcy leak speed: thesis of S. Kerzalé (2010-2013) with the LEMTA, University of Lorraine (France)
 - Detection/localization algorithms provided to the measurement and auscultation EDF department
 - Quantification algorithms transferred in the next years





Contribution of new technologies for the monitoring of hydraulic plants:

- Detection/localizations algorithms
 - □ First step: PCA
 - □ The first component is much more energetic than the following ones: it represents the "ground response" and is subtracted before \mathbf{Y} = continuing the processing

$$Y_{residue} = Y - Y_{signal}$$





- Detection/localizations algorithms
 - The first proposed approach combined ICA and PCA



m = number of singular values to construct 1st signal subspace

i = number of sources to be estimated by ICA

 i_2 = number of ICA sources to construct 2nd signal subspace



Detection/localizations algorithms

- Evolutions of the algorithm
 - Precipitations modify the behavior of the temperature: a test based on higher-order statistics (kurtosis) has been developed to automatically select the homogenous time intervals
 - Reduction of the time period to perform the PCA: under the hypothesis that leaks zones are sparse, a PCA on 24h data permits to identify regular zones from singular ones by comparing the profile at each distance with the one obtained as the first singular vector
 - When the two profiles are too much different, a singularity can be supposed
 - The remaining question is to get sufficient comparison elements to be sure that the singularities seen by the algorithm are effectively leaks





- Leak Darcy speed quantification
 - Once a leak has been detected, the next question is to evaluate the speed of the flow, which is the indicator for the stability of the dyke
 - □ In this case, there is a need for a data-model comparison
 - □ Two great categories of model can be used:
 - Physics-based quite simple transfer function model: thesis of P. Cunat with EDF measurement department and LTHE laboratory in Grenoble
 - 2D PDE model for hydrogeology associated with a 1D thermal model (advection-dispersiondiffusion): thesis of S. Kerzalé with EDF R&D and LEMTA laboratory in Nancy
 - □ The two approaches need to know air temperature and water temperature
 - The first approach is more consuming in data duration, because it needs to calibrate the model parameters while estimating the speed



- 2D Hydrogeological model
 - Conservation law on the piezometric head (~water pressure) coupled with the Richards' equation

$$[S_0 S(\psi) + \mathcal{E} \partial_{\psi} S(\psi)] \partial_t \psi = f_{\mu} \partial_x [K_h K(S(\psi)) \partial_x \psi] + f_{\mu} \partial_x [K_v K(S(\psi)) \partial_y (\psi + y)]$$

• K_h and K_v horizontal and vertical permeabilities (different because of the soil compaction) and K(S) relative permeability function of the saturation (itself function of the piezometric head like Van Genuchten model)





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- 2D Hydrogeological model
 - Piezometric head at equilibrium



Horizontal velocity at equilibrium





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- 2D Thermal model
 - Conservation law on the temperature coupled with the Fourier law

$$(\varepsilon S(\psi)(\rho C)^{w} + (1 - \varepsilon)(\rho C)^{m}) \partial_{t}T + (\rho C)^{w} \vec{v}.\vec{\nabla}T = div(\Lambda \vec{\nabla}T)$$

□ 2D model used for simulation and comparison with the 1D case in estimation





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Diffusion

- Leak velocity estimation
 - □ First method: Extended Kalman Filter (EKF) on a 1D thermal model
 - Simultaneous reconstruction of the temperature on a current line of the 2D hydrogeological model and of the leak velocity: pertinent for quite important velocities



Leak velocity estimation

- Second method: Extended Kalman Filter (EKF) on a 1D thermal model with initial condition estimation
 - First step: For a given initial condition simultaneous reconstruction of the temperature on a current line of the 2D hydrogeological model and of the leak velocity
 - Second step: Application of a Kalman smoother to take in account the information in the future, update of the initial condition. Goto the first step until convergence
 - This method allows to deal with weaker leak velocities
- Third method: Optimization on a time interval, simultaneous estimation of initial condition and leak velocity, optimal control-like algorithm (adjoint problem)



- Leak velocity estimation
 - □ Fourth method: Stochastic algorithm Particle Swarm Optimization
 - P_i: best particle position
 - P_q : best position among the best particle positions

$$V_i^{k+1} = \omega V_i^k + b_1 \left(P_i - \beta_i^k \right) + b_2 \left(P_g - \beta_i^k \right)$$

$$\beta_i^{k+1} = \beta_i^k + V_i^{k+1},$$



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EDF context

- Always with the dykes, one other main subject of monitoring is the evolution of the ground
- One major problem is the existence of sinkholes (kind of cavity) which can collapse, especially in clay soils

EDF objective

- EDF searches for a continuous measurement capable of "seeing" distributed deformations
- The only way to make this distance-along deformation measurement is also using the fiber optic



- Measuring deformation with fiber optic : how does it work ?
 - □ Two effects are sensible to the deformations, Brillouin and Rayleigh:
 - Brillouin effect induces a frequency shift which is proportional to the deformation.
 - Rayleigh effect induces an amplitude modification
 - These two effects depend also on temperature. An unmixing can be necessary.

Technology principles

- The Brillouin devices are based on Stimulated Brillouin Scattering
 - An interrogator sends a laser pulse beam at one end of the fiber optic and analyses the backscattered light. This Brillouin effect measurement is called Optical Time-domain Analysis. The device estimates a frequency spectrum from which it extracts the shift of the maximum.



Technology principles (followed)

- The Rayleigh devices exploit Optical Time-domain Reflectometry or Optical Frequencydomain Reflectometry: a frequency sweep is sent in the fiber optic and the scattering is correlated with the sweep to obtain the information. EDF uses OFDR.
- Brillouin sensor is efficient on several kilometers with an half-meter resolution whereas Rayleigh sensor is efficient only on only one hundred meters.
- Question: how getting more resolution from Brillouin devices in areas where deformation changes ?

Improvement of the Brillouin resolution measurement

- □ Framework: thesis with the Gipsa-lab (E. Buchoud, director: J.I. Mars)
- □ Guidelines:
 - Measurement:
 - On each position *x*, the Brillouin fiber optic response is an elementary spectrum (S_e) centered on a given frequency ($v_B(x)$).
 - The measured information is the integration of these elementary spectra on one meter long, with an overlapping of about one half-meter.

$$\tilde{G}(v, z_k) = \int_{z_k - w/2}^{z_k + w/2} S_e(v - v_B(x)) dx$$



Improvement of the Brillouin resolution measurement

- □ Guidelines (followed):
 - Signal processing:
 - The main hypothesis is that the deformation is piecewise-constant
 - Separation of the elementary spectra (S_e) knowing the theoretical shape of this spectrum and using a nonnegative least-squares method or a nonnegative source separation algorithm
 - An heuristic has been developed to exploit the parameters of the mixing (amplitudes and central frequencies of the spectra) to extrapolate the deformation information
 - A classical inverse problem with regularization is also tested with good results



Description of the heuristic méthod





- Results: comparison with the Rayleigh measurement
 - Heuristic method
 - Heuristic: red and blue (depends on signal decomposition method)
 - Rayleigh: black



□ Inverse problem



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EDF context

- □ The dams present two sorts of displacement:
 - reversible: due to temperature, water height, seasonality
 - irreversible: due to ground movements, ageing, ...
- The dykes present also a irreversible component
- The question is to be able to measure the global displacement. Then, by signal processing, it is possible to extract the irreversible component
- The current measurement system consists in pendulums which are in the dams and whose data are read every year.
- □ Topometric tests are also made.
- □ A collaboration with the Gipsa-lab is done (G. Vasile) through a thesis in particular

EDF objective

- □ The question is to be able to measure the displacement more frequently.
- The proposal is by using radar satellite interferometry which can moreover carry out a better precision.



Radar Satellite Interferometry: principles

Two synthesis aperture radar (SAR) satellites (e.g. TerraSAR-X) emit plane waves on the same point with slightly different positions: the two beams interfere and the resulting complex signal is measured.

Orbit 2

Time 1

- Several effects modify the phase difference which have to be eliminated to get the interesting information:
 - Orbital correction
 - Atmospheric turbulences
 - Noise
 - Topographic effect



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Orbit 1 Time T.

Signal processing

- The objective is to detect permanent scatterers in the image: the displacement measurement is based on the computation of the displacement estimation of these points
- The processing is based on a statistical point of view of the image: the image is a mixing of a complex texture (the clutter) is seen as a realization of a density of probability (Spherical Independent Random Vector) and of punctual variations (the permanent scatterers)
- □ A hypothesis test is performed to detect if a point belongs to the clutter (hypothesis H_0) or is a sum of a target vector and the clutter (hypothesis H_1)

$$\begin{cases} H_0: \mathbf{k} = \mathbf{c} \\ H_1: \mathbf{k} = \alpha \mathbf{p} + \mathbf{c} \end{cases} \Lambda([M]) = \frac{p_{\mathbf{k}}(\mathbf{k}/H_1)}{p_{\mathbf{k}}(\mathbf{k}/H_0)} = \frac{h_p\left((\mathbf{k} - \mathbf{p})^H[M]^{-1}(\mathbf{k} - \mathbf{p})\right)}{h_p\left(\mathbf{k}^H[M]^{-1}\mathbf{k}\right)} \overset{H_1}{\underset{H_0}{\gtrless}} \lambda$$
$$\Lambda([M]) = \frac{|\mathbf{p}^H[M]^{-1}\mathbf{k}|^2}{(\mathbf{p}^H[M]^{-1}\mathbf{p})\left(\mathbf{k}^H[M]^{-1}\mathbf{k}\right)} \overset{H_1}{\underset{H_0}{\gtrless}} \lambda$$



- Example on the Barrage of Puylaurent
 - Detection of Permanent Scatterers
 - Displacement field computation
- SAR in X band also useful for estimating snow water equivalent (thesis with Gipsalab, N. Besic, director: G. Vasile)



THANK YOU FOR YOUR ATTENTION ANY QUESTION ?



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